Proof The proof is indirect. We will assume that $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ are linearly dependent and show that this assumption leads to a contradiction.

If $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ are linearly dependent, then one of these vectors must be expressible as a linear combination of the previous ones. Let \mathbf{v}_{k+1} be the first of the vectors \mathbf{v}_i that can be so expressed. In other words, $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ are linearly independent, but there are scalars c_1, c_2, \ldots, c_k such that

$$\mathbf{v}_{k+1} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_k \mathbf{v}_k \tag{1}$$

Multiplying both sides of equation (1) by A from the left and using the fact that $A\mathbf{v}_i$ = $\lambda_i \mathbf{v}_i$ for each i, we have

$$\lambda_{k+1}\mathbf{v}_{k+1} = A\mathbf{v}_{k+1} = A(c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_k\mathbf{v}_k)$$

$$= c_1A\mathbf{v}_1 + c_2A\mathbf{v}_2 + \dots + c_kA\mathbf{v}_k$$

$$= c_1\lambda_1\mathbf{v}_1 + c_2\lambda_2\mathbf{v}_2 + \dots + c_k\lambda_k\mathbf{v}_k$$
(2)

Now we multiply both sides of equation (1) by λ_{k+1} to get

$$\lambda_{k+1} \mathbf{v}_{k+1} = c_1 \lambda_{k+1} \mathbf{v}_1 + c_2 \lambda_{k+1} \mathbf{v}_2 + \dots + c_k \lambda_{k+1} \mathbf{v}_k$$
(3)

When we subtract equation (3) from equation (2), we obtain

$$\mathbf{0} = c_1(\lambda_1 - \lambda_{k+1})\mathbf{v}_1 + c_2(\lambda_2 - \lambda_{k+1})\mathbf{v}_2 + \cdots + c_k(\lambda_k - \lambda_{k+1})\mathbf{v}_k$$

The linear independence of $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ implies that

$$c_1(\lambda_1 - \lambda_{k+1}) = c_2(\lambda_2 - \lambda_{k+1}) = \cdots = c_k(\lambda_k - \lambda_{k+1}) = 0$$

Since the eigenvalues λ_i are all distinct, the terms in parentheses $(\lambda_i - \lambda_{k+1})$, $i=1,\ldots,k$, are all nonzero. Hence, $c_1=c_2=\cdots=c_k=0$. This implies that

$$\mathbf{v}_{k+1} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \cdots + c_k \mathbf{v}_k = 0 \mathbf{v}_1 + 0 \mathbf{v}_2 + \cdots + 0 \mathbf{v}_k = \mathbf{0}$$

which is impossible, since the eigenvector \mathbf{v}_{k+1} cannot be zero. Thus, we have a contradiction, which means that our assumption that $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ are linearly dependent is false. It follows that $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ must be linearly independent.

Exercises 4.3

In Exercises 1-12, compute (a) the characteristic polynomial of A, (b) the eigenvalues of A, (c) a basis for each eigenspace of A, and (d) the algebraic and geometric multiplicity of each eigenvalue.

1.
$$A = \begin{bmatrix} 1 & 3 \\ -2 & 6 \end{bmatrix}$$
 2. $A = \begin{bmatrix} 2 & 1 \\ -1 & 0 \end{bmatrix}$
• 3. $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & -2 & 1 \\ 0 & 0 & 3 \end{bmatrix}$ • 4. $A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$
• 5. $A = \begin{bmatrix} 1 & 2 & 0 \\ -1 & -1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$ • 6. $A = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -1 & 3 \\ 2 & 0 & 1 \end{bmatrix}$

The Exercises 1–12, compute (a) the characteristic polynomial of A, (b) the eigenvalues of A, (c) a basis for each eigenspace of A, and (d) the algebraic and geometric multiplicity of each eigenvalue.

1.
$$A = \begin{bmatrix} 1 & 3 \\ -2 & 6 \end{bmatrix}$$
2. $A = \begin{bmatrix} 2 & 1 \\ -1 & 0 \end{bmatrix}$
3. $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & -2 & 1 \\ 0 & 0 & 3 \end{bmatrix}$
4. $A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$
4. $A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$
5. $A = \begin{bmatrix} 1 & 2 & 0 \\ -1 & -1 & 1 \\ 0 & 0 & 3 \end{bmatrix}$
6. $A = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -1 & 3 \\ 2 & 0 & 1 \end{bmatrix}$
6. $A = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -1 & 3 \\ 2 & 0 & 1 \end{bmatrix}$
6. $A = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -1 & 3 \\ 2 & 0 & 1 \end{bmatrix}$
6. $A = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -1 & 3 \\ 2 & 0 & 1 \end{bmatrix}$
6. $A = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -1 & 3 \\ 2 & 0 & 1 \end{bmatrix}$
6. $A = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -1 & 3 \\ 2 & 0 & 1 \end{bmatrix}$
6. $A = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -1 & 3 \\ 2 & 0 & 1 \end{bmatrix}$
6. $A = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -1 & 3 \\ 2 & 0 & 1 \end{bmatrix}$
6. $A = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -1 & 3 \\ 2 & 0 & 1 \end{bmatrix}$
7. $A = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ -1 & 0 & 2 \end{bmatrix}$
7. $A = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ -1 & 0 & 2 \end{bmatrix}$
7. $A = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ -1 & 0 & 2 \end{bmatrix}$
7. $A = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ -1 & 0 & 2 \end{bmatrix}$
7. $A = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ -1 & 0 & 2 \end{bmatrix}$
7. $A = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ -1 & 0 & 2 \end{bmatrix}$
7. $A = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ -1 & 0 & 2 \end{bmatrix}$
7. $A = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ -1 & 0 & 2 \end{bmatrix}$
7. $A = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ -1 & 0 & 2 \end{bmatrix}$
8. $A = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 2 & 0 \\ -1 & 1 & 1 \end{bmatrix}$
9. $A = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 4 & 5 \\ 0 & 0 & 1 & 1 \end{bmatrix}$
9. $A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 1 & 3 & 0 \\ -2 & 1 & 2 & -1 \end{bmatrix}$

- $\bullet 12. A = \begin{bmatrix} 4 & 0 & 1 & 0 \\ 0 & 4 & 1 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 3 & 0 \end{bmatrix}$
 - 13. Prove Theorem 4.18(b).
 - 14. Prove Theorem 4.18(c). [*Hint:* Combine the proofs of parts (a) and (b) and see the fourth Remark following Theorem 3.9 (p. 167).]

In Exercises 15 and 16, A is a 2×2 matrix with eigenvectors $\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ corresponding to eigenvalues $\lambda_1 = \frac{1}{2}$ and $\lambda_2 = 2$, respectively, and $\mathbf{x} = \begin{bmatrix} 5 \\ 1 \end{bmatrix}$.

- 15. Find A¹⁰x.
 - 16. Find $A^k \mathbf{x}$. What happens as k becomes large (i.e., $k \to \infty$)?

In Exercises 17 and 18, A is a 3×3 matrix with eigenvectors

The Exercises 17 and 16, A is a
$$3 \times 3$$
 matrix. With eigenvectors $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, and \mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ corresponding to eigenvalues $\lambda_1 = -\frac{1}{3}$, $\lambda_2 = \frac{1}{3}$, and $\lambda_3 = 1$, respectively, and $\mathbf{x} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$.

- 17. Find A²⁰ x.
 - **18.** Find $A^k \mathbf{x}$. What happens as k becomes large (i.e., $k \to \infty$)?
- 19. (a) Show that, for any square matrix A, A^T and A have the same characteristic polynomial and hence the same eigenvalues.
 - (b) Give an example of a 2×2 matrix A for which A^T and A have different eigenspaces.
- **20.** Let *A* be a nilpotent matrix (that is, $A^m = O$ for some m > 1). Show that $\lambda = 0$ is the only eigenvalue of *A*.
- 21. Let A be an idempotent matrix (that is, $A^2 = A$). Show that $\lambda = 0$ and $\lambda = 1$ are the only possible eigenvalues of A.
- 22. If \mathbf{v} is an eigenvector of A with corresponding eigenvalue λ and c is a scalar, show that \mathbf{v} is an eigenvector of A-cI with corresponding eigenvalue $\lambda-c$.
- 23. (a) Find the eigenvalues and eigenspaces of

$$A = \begin{bmatrix} 3 & 2 \\ 5 & 0 \end{bmatrix}$$

- (b) Using Theorem 4.18 and Exercise 22, find the eigenvalues and eigenspaces of A^{-1} , A = 2I, and A + 2I.
- 24. Let A and B be $n \times n$ matrices with eigenvalues λ and μ , respectively.
 - (a) Give an example to show that $\lambda + \mu$ need not be an eigenvalue of A + B.
 - (b) Give an example to show that $\lambda\mu$ need not be an eigenvalue of AB.
 - (c) Suppose λ and μ correspond to the same eigenvector \mathbf{x} . Show that, in this case, $\lambda + \mu$ is an eigenvalue of A + B and $\lambda \mu$ is an eigenvalue of AB.
- 25. If A and B are two row equivalent matrices, do they necessarily have the same eigenvalues? Either prove that they do or give a counterexample.

Let p(x) be the polynomial

$$p(x) = x^{n} + a_{n-1}x^{n-1} + \cdots + a_{1}x + a_{0}$$

The companion matrix of p(x) is the $n \times n$ matrix

$$C(p) = \begin{bmatrix} -a_{n-1} & -a_{n-2} & \cdots & -a_1 & -a_0 \\ 1 & 0 & \cdots & 0 & 0 \\ 0 & 1 & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \cdots & 1 & 0 \end{bmatrix}$$
 (4)

- **26.** Find the companion matrix of $p(x) = x^2 7x + 12$ and then find the characteristic polynomial of C(p).
- 27. Find the companion matrix of $p(x) = x^3 + 3x^2 4x + 12$ and then find the characteristic polynomial of C(p).
- **28.** (a) Show that the companion matrix C(p) of $p(x) = x^2 + ax + b$ has characteristic polynomial $\lambda^2 + a\lambda + b$.
 - (b) Show that if λ is an eigenvalue of the companion matrix C(p) in part (a), then $\begin{bmatrix} \lambda \\ 1 \end{bmatrix}$ is an eigenvector of C(p) corresponding to λ .
- **29.** (a) Show that the companion matrix C(p) of $p(x) = x^3 + ax^2 + bx + c$ has characteristic polynomial $-(\lambda^3 + a\lambda^2 + b\lambda + c)$.
 - (b) Show that if λ is an eigenvalue of the companion

matrix C(p) in part (a), then $\begin{bmatrix} \lambda^2 \\ \lambda \\ 1 \end{bmatrix}$ is an eigenvector of C(p) corresponding to λ .

Solving for A, we have $A = PDP^{-1}$, which makes it easy to find powers of A. We compute

$$A^{2} = (PDP^{-1})(PDP^{-1}) = PD(P^{-1}P)DP^{-1} = PDIDP^{-1} = PD^{2}P^{-1}$$



and, generally, $A^n = PD^nP^{-1}$ for all $n \ge 1$. (You should verify this by induction. Observe that this fact will be true for *any* diagonalizable matrix, not just the one in this example.)

Since

$$D^n = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}^n = \begin{bmatrix} (-1)^n & 0 \\ 0 & 2^n \end{bmatrix}$$

we have

$$A^{n} = PD^{n}P^{-1} = \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} (-1)^{n} & 0 \\ 0 & 2^{n} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix}^{-1}$$

$$= \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} (-1)^{n} & 0 \\ 0 & 2^{n} \end{bmatrix} \begin{bmatrix} \frac{2}{3} & -\frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{2(-1)^{n} + 2^{n}}{3} & \frac{(-1)^{n+1} + 2^{n}}{3} \\ \frac{2(-1)^{n+1} + 2^{n+1}}{3} & \frac{(-1)^{n+2} + 2^{n+1}}{3} \end{bmatrix}$$

Since we were only asked for A^{10} , this is more than we needed. But now we can simply set n = 10 to find

$$A^{10} = \begin{bmatrix} \frac{2(-1)^{10} + 2^{10}}{3} & \frac{(-1)^{11} + 2^{10}}{3} \\ \frac{2(-1)^{11} + 2^{11}}{3} & \frac{(-1)^{12} + 2^{11}}{3} \end{bmatrix} = \begin{bmatrix} 342 & 341 \\ 682 & 683 \end{bmatrix}$$



Exercises 4.4

In Exercises 1–4, show that A and B are not similar matrices.

• 1.
$$A = \begin{bmatrix} 4 & 1 \\ 3 & 1 \end{bmatrix}$$
, $B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

2.
$$A = \begin{bmatrix} 3 & -1 \\ -5 & 7 \end{bmatrix}, B = \begin{bmatrix} 2 & 1 \\ -4 & 6 \end{bmatrix}$$

$$\bullet_{3. A} = \begin{bmatrix} 2 & 1 & 4 \\ 0 & 2 & 3 \\ 0 & 0 & 4 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 4 & 0 \\ 2 & 3 & 4 \end{bmatrix}$$

$$\bullet 4. A = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & -1 \\ 0 & -1 & 1 \end{bmatrix}, B = \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix}$$

In Exercises 5–7, a diagonalization of the matrix A is given in the form $P^{-1}AP = D$. List the eigenvalues of A and bases for the corresponding eigenspaces.

• 5.
$$\begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 5 & -1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 4 & 0 \\ 0 & 3 \end{bmatrix}$$

$$\bullet 6. \begin{bmatrix} \frac{1}{6} & \frac{1}{6} & \frac{1}{6} \\ \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} \\ \frac{1}{3} & \frac{1}{3} & -\frac{2}{3} \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 3 & 1 & 0 \\ 1 & -1 & 1 \\ 2 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

$$\bullet 7. \begin{bmatrix} \frac{1}{8} & \frac{1}{8} & \frac{1}{8} \\ -\frac{1}{4} & \frac{3}{4} & -\frac{1}{4} \\ \frac{5}{8} & -\frac{3}{8} & -\frac{3}{8} \end{bmatrix} \begin{bmatrix} 1 & 3 & 3 \\ 2 & 0 & 2 \\ 3 & 3 & 1 \end{bmatrix} \begin{bmatrix} 3 & 0 & 1 \\ 2 & 1 & 0 \\ 3 & -1 & -1 \end{bmatrix} = \begin{bmatrix} 6 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

In Exercises 8-15, determine whether A is diagonalizable and, if so, find an invertible matrix P and a diagonal matrix D such that $P^{-1}AP = D$.

8.
$$A = \begin{bmatrix} 5 & 2 \\ 2 & 5 \end{bmatrix}$$

• 9. $A = \begin{bmatrix} -3 & 4 \\ -1 & 1 \end{bmatrix}$

10. $A = \begin{bmatrix} 3 & 1 & 0 \\ 0 & 3 & 1 \\ 0 & 0 & 3 \end{bmatrix}$

• 11. $A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$

12. $A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 2 & 1 \\ 3 & 0 & 1 \end{bmatrix}$

• 13. $A = \begin{bmatrix} 1 & 2 & 1 \\ -1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$

14. $A = \begin{bmatrix} 2 & 0 & 0 & 2 \\ 0 & 3 & 2 & 1 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

• 15. $A = \begin{bmatrix} 2 & 0 & 0 & 4 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & -2 \end{bmatrix}$

16. $A = \begin{bmatrix} 3 & 1 \\ 0 & -1 \end{bmatrix}, B = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$

In Exercises 16-23, use the method of Example 4.29 to compute the indicated power of the matrix.

16.
$$\begin{bmatrix} -4 & 6 \\ -3 & 5 \end{bmatrix}^{9}$$
17.
$$\begin{bmatrix} -1 & 6 \\ 1 & 0 \end{bmatrix}^{10}$$
18.
$$\begin{bmatrix} 4 & -3 \\ -1 & 2 \end{bmatrix}^{-6}$$
19.
$$\begin{bmatrix} 0 & 3 \\ 1 & 2 \end{bmatrix}^{k}$$
20.
$$\begin{bmatrix} 2 & 1 & 2 \\ 2 & 1 & 2 \\ 2 & 1 & 2 \end{bmatrix}^{8}$$
21.
$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}^{2002}$$
22.
$$\begin{bmatrix} 2 & 0 & 1 \\ 1 & 1 & 1 \\ 1 & 0 & 2 \end{bmatrix}^{-5}$$
23.
$$\begin{bmatrix} 1 & 1 & 0 \\ 2 & -2 & 2 \\ 0 & 1 & 1 \end{bmatrix}^{k}$$

In Exercises 24-29, find all (real) values of k for which A is diagonalizable.

24.
$$A = \begin{bmatrix} 1 & 1 \\ 0 & k \end{bmatrix}$$
 25. $A = \begin{bmatrix} 1 & k \\ 0 & 1 \end{bmatrix}$ **26.** $A = \begin{bmatrix} k & 1 \\ 1 & 0 \end{bmatrix}$ **27.** $A = \begin{bmatrix} 1 & 0 & k \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$\mathbf{28.} \ A = \begin{bmatrix} 1 & k & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \qquad \mathbf{29.} \ A = \begin{bmatrix} 1 & 1 & k \\ 1 & 1 & k \\ 1 & 1 & k \end{bmatrix}$$

- **30.** Prove Theorem 4.21(c).
- 31. Prove Theorem 4.22(b).
- 32. Prove Theorem 4.22(c).
- 33. Prove Theorem 4.22(e).
- 34. If A and B are invertible matrices, show that AB and BA are similar.
- 35. Prove that if A and B are similar matrices, then tr(A) = tr(B). (Hint: Find a way to use Exercise 45

In general, it is difficult to show that two matrices are similar. However, if two similar matrices are diagonalizable, the task becomes easier. In Exercises 36-39, show that A and B are similar by showing that they are similar to the same diagonal matrix. Then find an invertible matrix P such that

37.
$$A = \begin{bmatrix} 5 & -3 \\ 4 & -2 \end{bmatrix}, B = \begin{bmatrix} -1 & 1 \\ -6 & 4 \end{bmatrix}$$
38. $A = \begin{bmatrix} 2 & 1 & 0 \\ 0 & -2 & 1 \\ 0 & 0 & 1 \end{bmatrix}, B = \begin{bmatrix} 3 & 2 & -5 \\ 1 & 2 & -1 \\ 2 & 2 & -4 \end{bmatrix}$
39. $A = \begin{bmatrix} 1 & 0 & 2 \\ 1 & -1 & 1 \\ 2 & 0 & 1 \end{bmatrix}, B = \begin{bmatrix} -3 & -2 & 0 \\ 6 & 5 & 0 \\ 4 & 4 & -1 \end{bmatrix}$

- 40. Prove that if A is similar to B, then A^T is similar to B^T .
- 41. Prove that if A is diagonalizable, so is A^T .
 - 42. Let A be an invertible matrix. Prove that if A is diagonalizable, so is A^{-1} .
 - 43. Prove that if A is a diagonalizable matrix with only one eigenvalue λ , then A is of the form $A = \lambda I$. (Such a matrix is called a scalar matrix.)
- 44. Let A and B be $n \times n$ matrices, each with n distinct eigenvalues. Prove that A and B have the same eigenvectors if and only if AB = BA.
- 45. Let A and B be similar matrices. Prove that the algebraic multiplicities of the eigenvalues of A and B are the same.