- 17. Prove Theorem 3.2(a)-(d).
- 18. Prove Theorem 3.2(e)-(h).
- 19. Prove Theorem 3.3(c).
- 20. Prove Theorem 3.3(d).
- 21. Prove the half of Theorem 3.3(e) that was not proved in the text.
- 22. Prove that, for square matrices A and B, AB = BA if and only if $(A B)(A + B) = A^2 B^2$.

In Exercises 23–25, if $B = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, find conditions on a, b, c, and d such that AB = BA.

23.
$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$
 24. $A = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$ **25.** $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

- **26.** Find conditions on a, b, c, and d such that $B = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ commutes with both $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ and $\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$.
- 27. Find conditions on a, b, c, and d such that $B = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ commutes with every 2×2 matrix.
- **28.** Prove that if *AB* and *BA* are both defined, then *AB* and *BA* are both square matrices.

A square matrix is called **upper triangular** if all of the entries below the main diagonal are zero. Thus, the form of an upper triangular matrix is

$$\begin{bmatrix} * & * & \dots & * & * \\ 0 & 0 & \ddots & \vdots & \vdots \\ \vdots & \vdots & & * & * \\ 0 & 0 & \dots & 0 & * \end{bmatrix}$$

where the entries marked * are arbitrary. A more formal definition of such a matrix $A = [a_{ij}]$ is that $a_{ij} = 0$ if i > j.

- **29.** Prove that the product of two upper triangular $n \times n$ matrices is upper triangular.
- **30.** Prove Theorem 3.4(a)-(c).
- 31. Prove Theorem 3.4(e).
- 32. Using induction, prove that for all $n \ge 1$, $(A_1 + A_2 + \cdots + A_n)^T = A_1^T + A_2^T + \cdots + A_n^T$
- **33.** Using induction, prove that for all $n \ge 1$, $(A_1 A_2 \cdots A_n)^T = A_n^T \cdots A_2^T A_1^T$.
- 34. Prove Theorem 3.5(b).

- 35. (a) Prove that if A and B are symmetric $n \times n$ matrices, then so is A + B.
 - (b) Prove that if A is a symmetric $n \times n$ matrix, then so is kA for any scalar k.
- 36. (a) Give an example to show that if A and B are symmetric $n \times n$ matrices, then AB need not be symmetric.
 - (b) Prove that if A and B are symmetric $n \times n$ matrices, then AB is symmetric if and only if AB = BA.

A square matrix is called **skew-symmetric** if $A^T = -A$.

37. Which of the following matrices are skew-symmetric?

(a)
$$\begin{bmatrix} 1 & 2 \\ -2 & 3 \end{bmatrix}$$
 (b) $\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ (c) $\begin{bmatrix} 0 & 3 & -1 \\ -3 & 0 & 2 \\ 1 & -2 & 0 \end{bmatrix}$ (d) $\begin{bmatrix} 0 & 1 & 2 \\ -1 & 0 & 5 \\ 2 & 5 & 0 \end{bmatrix}$

- **38.** Give a componentwise definition of a skew-symmetric matrix.
- <u>39.</u> Prove that the main diagonal of a skew-symmetric matrix must consist entirely of zeros.
- **40.** Prove that if A and B are skew-symmetric $n \times n$ matrices, then so is A + B.
- **41.** If *A* and *B* are skew-symmetric 2×2 matrices, under what conditions is *AB* skew-symmetric?
- **42.** Prove that if A is an $n \times n$ matrix, then $A A^T$ is skew-symmetric.
- **43.** (a) Prove that any square matrix *A* can be written as the sum of a symmetric matrix and a skew-symmetric matrix. (*Hint:* Consider Theorem 3.5 and Exercise 42).
 - (b) Illustrate part (a) for the matrix $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$.

The **trace** of an $n \times n$ matrix $A = [a_{ij}]$ is the sum of the entries on its main diagonal and is denoted by tr(A). That is,

$$tr(A) = a_{11} + a_{22} + \cdots + a_{nn}$$

- **44.** If A and B are $n \times n$ matrices, prove the following properties of the trace:
 - (a) $\operatorname{tr}(A + B) = \operatorname{tr}(A) + \operatorname{tr}(B)$
 - **(b)** tr(kA) = ktr(A), where k is a scalar
- **45.** Prove that if A and B are $n \times n$ matrices, then tr(AB) = tr(BA).
- 46. If A is any matrix, to what is $tr(AA^T)$ equal?
- 47. Show that there are no 2×2 matrices A and B such that $AB BA = I_2$.

In each case, find an elementary matrix E that satisfies the given equation.

24.
$$EA = B$$

25.
$$EB = A$$

26.
$$EA = C$$

27.
$$EC = A$$

28.
$$EC = D$$

29.
$$ED = C$$

30. Is there an elementary matrix E such that EA = D? Why or why not?

In Exercises 31–38, find the inverse of the given elementary matrix.

$$\mathbf{31.} \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix}$$

32.
$$\begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$

33.
$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

34.
$$\begin{bmatrix} 1 & 0 \\ -\frac{1}{2} & 1 \end{bmatrix}$$

$$\mathbf{35.} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{36.} \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

37.
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & c & 0 \\ 0 & 0 & 1 \end{bmatrix}, c \neq 0$$

38.
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix}, c \neq 0$$

In Exercises 39 and 40, find a sequence of elementary matrices E_1, E_2, \ldots, E_k such that $E_k \cdots E_2 E_1 A = I$. Use this sequence to write both A and A^{-1} as products of elementary matrices.

39.
$$A = \begin{bmatrix} 1 & 0 \\ -1 & -2 \end{bmatrix}$$
 40. $A = \begin{bmatrix} 2 & 4 \\ 1 & 1 \end{bmatrix}$

40.
$$A = \begin{bmatrix} 2 & 4 \\ 1 & 1 \end{bmatrix}$$

- **41.** Prove Theorem 3.13 for the case of AB = I.
- **42.** (a) Prove that if A is invertible and AB = O, then B = O.
 - (b) Give a counterexample to show that the result in part (a) may fail if A is not invertible.
- **43.** (a) Prove that if A is invertible and BA = CA, then
 - (b) Give a counterexample to show that the result in part (a) may fail if A is not invertible.
- **44.** A square matrix A is called *idempotent* if $A^2 = A$. (The word idempotent comes from the Latin idem, meaning "same," and potere, meaning "to have power." Thus, something that is idempotent has the "same power" when squared.)
 - (a) Find three idempotent 2×2 matrices.
 - **(b)** Prove that the only invertible idempotent $n \times n$ matrix is the identity matrix.
- 45. Show that if A is a square matrix that satisfies the equation $A^{2} - 2A + I = O$, then $A^{-1} = 2I - A$.

- 46. Prove that if a symmetric matrix is invertible, then its inverse is symmetric also.
- 47. Prove that if A and B are square matrices and AB is invertible, then both A and B are invertible.

In Exercises 48-63, use the Gauss-Jordan method to find the inverse of the given matrix (if it exists).

48.
$$\begin{bmatrix} 1 & 3 \\ 2 & 5 \end{bmatrix}$$

49.
$$\begin{bmatrix} -2 & 4 \\ 3 & -1 \end{bmatrix}$$

$$50. \begin{bmatrix} 6 & -4 \\ -3 & 2 \end{bmatrix}$$

51.
$$\begin{bmatrix} 1 & a \\ -a & 1 \end{bmatrix}$$

$$\mathbf{52.} \begin{bmatrix} 2 & 3 & 0 \\ 1 & -2 & -1 \\ 2 & 0 & -1 \end{bmatrix}$$

$$\mathbf{54.} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

56.
$$\begin{bmatrix} 0 & a & 0 \\ b & 0 & c \\ 0 & d & 0 \end{bmatrix}$$

$$\underline{58}. \begin{bmatrix}
\sqrt{2} & 0 & 2\sqrt{2} & 0 \\
-4\sqrt{2} & \sqrt{2} & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 3 & 1
\end{bmatrix}$$

$$\mathbf{59.} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ a & b & c & d \end{bmatrix}$$

60.
$$\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$$
 over \mathbb{Z}_2

61.
$$\begin{bmatrix} 4 & 2 \\ 3 & 4 \end{bmatrix}$$
 over \mathbb{Z}_5

62.
$$\begin{bmatrix} 2 & 1 & 0 \\ 1 & 1 & 2 \\ 0 & 2 & 1 \end{bmatrix}$$
 over \mathbb{Z}_3

63.
$$\begin{bmatrix} 1 & 5 & 0 \\ 1 & 2 & 4 \\ 3 & 6 & 1 \end{bmatrix}$$
 over \mathbb{Z}

Partitioning large square matrices can sometimes make their inverses easier to compute, particularly if the blocks have a nice form. In Exercises 64-68, verify by block multiplication that the inverse of a matrix, if partitioned as shown, is as claimed. (Assume that all inverses exist as needed.)

64.
$$\begin{bmatrix} A & B \\ O & D \end{bmatrix}^{-1} = \begin{bmatrix} A^{-1} & -A^{-1}BD^{-1} \\ O & D^{-1} \end{bmatrix}$$