Proof The proof is indirect. We will assume that $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ are linearly dependent and show that this assumption leads to a contradiction.

If $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ are linearly dependent, then one of these vectors must be expressible as a linear combination of the previous ones. Let \mathbf{v}_{k+1} be the first of the vectors \mathbf{v}_i that can be so expressed. In other words, $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ are linearly independent, but there are scalars c_1, c_2, \dots, c_k such that

$$\mathbf{v}_{k+1} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_k \mathbf{v}_k \tag{1}$$

Multiplying both sides of equation (1) by A from the left and using the fact that $A\mathbf{v}_i = \lambda_i \mathbf{v}_i$ for each i, we have

$$\lambda_{k+1} \mathbf{v}_{k+1} = A \mathbf{v}_{k+1} = A(c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_k \mathbf{v}_k)$$

$$= c_1 A \mathbf{v}_1 + c_2 A \mathbf{v}_2 + \dots + c_k A \mathbf{v}_k$$

$$= c_1 \lambda_1 \mathbf{v}_1 + c_2 \lambda_2 \mathbf{v}_2 + \dots + c_k \lambda_k \mathbf{v}_k$$
(2)

Now we multiply both sides of equation (1) by λ_{k+1} to get

$$\lambda_{k+1}\mathbf{v}_{k+1} = c_1\lambda_{k+1}\mathbf{v}_1 + c_2\lambda_{k+1}\mathbf{v}_2 + \dots + c_k\lambda_{k+1}\mathbf{v}_k \tag{3}$$

When we subtract equation (3) from equation (2), we obtain

$$\mathbf{0} = c_1(\lambda_1 - \lambda_{k+1})\mathbf{v}_1 + c_2(\lambda_2 - \lambda_{k+1})\mathbf{v}_2 + \cdots + c_k(\lambda_k - \lambda_{k+1})\mathbf{v}_k$$

The linear independence of $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ implies that

$$c_1(\lambda_1-\lambda_{k+1})=c_2(\lambda_2-\lambda_{k+1})=\cdots=c_k(\lambda_k-\lambda_{k+1})=0$$

Since the eigenvalues λ_i are all distinct, the terms in parentheses $(\lambda_i - \lambda_{k+1})$, $i = 1, \ldots, k$, are all nonzero. Hence, $c_1 = c_2 = \cdots = c_k = 0$. This implies that

$$\mathbf{v}_{k+1} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \cdots + c_k \mathbf{v}_k = 0 \mathbf{v}_1 + 0 \mathbf{v}_2 + \cdots + 0 \mathbf{v}_k = \mathbf{0}$$

which is impossible, since the eigenvector \mathbf{v}_{k+1} cannot be zero. Thus, we have a contradiction, which means that our assumption that $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ are linearly dependent is false. It follows that $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ must be linearly independent.

Exercises 4.3

In Exercises 1–12, compute (a) the characteristic polynomial of A, (b) the eigenvalues of A, (c) a basis for each eigenspace of A, and (d) the algebraic and geometric multiplicity of each eigenvalue.

1.
$$A = \begin{bmatrix} 1 & 3 \\ -2 & 6 \end{bmatrix}$$
2. $A = \begin{bmatrix} 2 & 1 \\ -1 & 0 \end{bmatrix}$
3. $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & -2 & 1 \\ 0 & 0 & 3 \end{bmatrix}$
4. $A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$
5. $A = \begin{bmatrix} 1 & 2 & 0 \\ -1 & -1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$
6. $A = \begin{bmatrix} 1 & 0 & 2 \\ 3 & -1 & 3 \\ 2 & 0 & 1 \end{bmatrix}$
11. $A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 1 & 3 & 0 \\ -2 & 1 & 2 & -1 \end{bmatrix}$

$$7. A = \begin{bmatrix} 4 & 0 & 1 \\ 2 & 3 & 2 \\ -1 & 0 & 2 \end{bmatrix}$$

$$8. A = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 2 & 0 \\ -1 & -1 & 1 \end{bmatrix}$$

$$9. A = \begin{bmatrix} 3 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$10. A = \begin{bmatrix} 2 & 1 & 1 & 0 \\ 0 & 1 & 4 & 5 \\ 0 & 0 & 3 & 1 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

$$11. A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 1 & 3 & 0 \\ -2 & 1 & 2 & -1 \end{bmatrix}$$

- 13. Prove Theorem 4.18(b).
- 14. Prove Theorem 4.18(c). [Hint: Combine the proofs of parts (a) and (b) and see the fourth Remark following Theorem 3.9 (p. 167).]

In Exercises 15 and 16, A is a 2×2 matrix with eigenvectors $\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ corresponding to eigenvalues $\lambda_1 = \frac{1}{2}$ and $\lambda_2 = 2$, respectively, and $\mathbf{x} = \begin{bmatrix} 5 \\ 1 \end{bmatrix}$.

- 15. Find A^{10} **x**.
- 16. Find $A^k \mathbf{x}$. What happens as k becomes large (i.e., $k \to \infty$)?

In Exercises 17 and 18, A is a 3×3 matrix with eigenvectors

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, and \mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} corresponding to eigenvalues $\lambda_1 = -\frac{1}{3}, \lambda_2 = \frac{1}{3}, and \lambda_3 = 1, respectively, and$$$

$$\mathbf{x} = \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}.$$

- 17. Find A^{20} x.
- 18. Find $A^k \mathbf{x}$. What happens as k becomes large (i.e., $k \to \infty$)?
- 19. (a) Show that, for any square matrix A, A^T and A have the same characteristic polynomial and hence the same eigenvalues.
 - (b) Give an example of a 2×2 matrix A for which A^T and A have different eigenspaces.
- 20. Let A be a nilpotent matrix (that is, $A^m = O$ for some m > 1). Show that $\lambda = 0$ is the only eigenvalue of A.
- 21. Let A be an idempotent matrix (that is, $A^2 = A$). Show that $\lambda = 0$ and $\lambda = 1$ are the only possible eigenvalues of A.
- 22. If \mathbf{v} is an eigenvector of A with corresponding eigenvalue λ and c is a scalar, show that \mathbf{v} is an eigenvector of A cI with corresponding eigenvalue λc .
- 23. (a) Find the eigenvalues and eigenspaces of

$$A = \begin{bmatrix} 3 & 2 \\ 5 & 0 \end{bmatrix}$$

- (b) Using Theorem 4.18 and Exercise 22, find the eigenvalues and eigenspaces of A^{-1} , A 2I, and A + 2I.
- 24. Let A and B be $n \times n$ matrices with eigenvalues λ and μ , respectively.
 - (a) Give an example to show that $\lambda + \mu$ need not be an eigenvalue of A + B.
 - (b) Give an example to show that $\lambda\mu$ need not be an eigenvalue of AB.
 - (c) Suppose λ and μ correspond to the *same* eigenvector \mathbf{x} . Show that, in this case, $\lambda + \mu$ is an eigenvalue of A + B and $\lambda \mu$ is an eigenvalue of AB.
- **25.** If A and B are two row equivalent matrices, do they necessarily have the same eigenvalues? Either prove that they do or give a counterexample.

Let p(x) be the polynomial

$$p(x) = x^{n} + a_{n-1}x^{n-1} + \cdots + a_1x + a_0$$

The companion matrix of p(x) is the $n \times n$ matrix

$$C(p) = \begin{bmatrix} -a_{n-1} & -a_{n-2} & \cdots & -a_1 & -a_0 \\ 1 & 0 & \cdots & 0 & 0 \\ 0 & 1 & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \cdots & 1 & 0 \end{bmatrix}$$
 (4)

- 26. Find the companion matrix of $p(x) = x^2 7x + 12$ and then find the characteristic polynomial of C(p).
- 27. Find the companion matrix of $p(x) = x^3 + 3x^2 4x + 12$ and then find the characteristic polynomial of C(p).
- 28. (a) Show that the companion matrix C(p) of $p(x) = x^2 + ax + b$ has characteristic polynomial $\lambda^2 + a\lambda + b$.
 - (b) Show that if λ is an eigenvalue of the companion matrix C(p) in part (a), then $\begin{bmatrix} \lambda \\ 1 \end{bmatrix}$ is an eigenvector of C(p) corresponding to λ .
- 29. (a) Show that the companion matrix C(p) of $p(x) = x^3 + ax^2 + bx + c$ has characteristic polynomial $-(\lambda^3 + a\lambda^2 + b\lambda + c)$.
 - (b) Show that if λ is an eigenvalue of the companion matrix C(p) in part (a), then $\begin{bmatrix} \lambda^2 \\ \lambda \\ 1 \end{bmatrix}$ is an eigenvector of C(p) corresponding to λ .

Solving for A, we have $A = PDP^{-1}$, which makes it easy to find powers of A. We compute

$$A^2 = (PDP^{-1})(PDP^{-1}) = PD(P^{-1}P)DP^{-1} = PDIDP^{-1} = PD^2P^{-1}$$



and, generally, $A^n = PD^nP^{-1}$ for all $n \ge 1$. (You should verify this by induction. Observe that this fact will be true for *any* diagonalizable matrix, not just the one in this example.)

Since

$$D^n = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}^n = \begin{bmatrix} (-1)^n & 0 \\ 0 & 2^n \end{bmatrix}$$

we have

$$A^{n} = PD^{n}P^{-1} = \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} (-1)^{n} & 0 \\ 0 & 2^{n} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix}^{-1}$$

$$= \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} (-1)^{n} & 0 \\ 0 & 2^{n} \end{bmatrix} \begin{bmatrix} \frac{2}{3} & -\frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{2(-1)^{n} + 2^{n}}{3} & \frac{(-1)^{n+1} + 2^{n}}{3} \\ \frac{2(-1)^{n+1} + 2^{n+1}}{3} & \frac{(-1)^{n+2} + 2^{n+1}}{3} \end{bmatrix}$$

Since we were only asked for A^{10} , this is more than we needed. But now we can simply set n = 10 to find

$$A^{10} = \begin{bmatrix} \frac{2(-1)^{10} + 2^{10}}{3} & \frac{(-1)^{11} + 2^{10}}{3} \\ \frac{2(-1)^{11} + 2^{11}}{3} & \frac{(-1)^{12} + 2^{11}}{3} \end{bmatrix} = \begin{bmatrix} 342 & 341 \\ 682 & 683 \end{bmatrix}$$



Exercises 4.4

In Exercises 1-4, show that A and B are not similar matrices.

1.
$$A = \begin{bmatrix} 4 & 1 \\ 3 & 1 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$
2. $A = \begin{bmatrix} 3 & -1 \\ -5 & 7 \end{bmatrix}, B = \begin{bmatrix} 2 & 1 \\ -4 & 6 \end{bmatrix}$
3. $A = \begin{bmatrix} 2 & 1 & 4 \\ 0 & 2 & 3 \\ 0 & 0 & 4 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 4 & 0 \\ 2 & 3 & 4 \end{bmatrix}$
4. $A = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & -1 \\ 0 & 1 & 0 \end{bmatrix}, B = \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix}$

In Exercises 5–7, a diagonalization of the matrix A is given in the form $P^{-1}AP = D$. List the eigenvalues of A and bases for the corresponding eigenspaces.

5.
$$\begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 5 & -1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 4 & 0 \\ 0 & 3 \end{bmatrix}$$
6.
$$\begin{bmatrix} \frac{1}{6} & \frac{1}{6} & \frac{1}{6} \\ \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} \\ \frac{1}{3} & \frac{1}{3} & -\frac{2}{3} \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 3 & 1 & 0 \\ 1 & -1 & 1 \\ 2 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

In Exercises 8-15, determine whether A is diagonalizable and, if so, find an invertible matrix P and a diagonal matrix D such that $P^{-1}AP = D$.

8.
$$A = \begin{bmatrix} 5 & 2 \\ 2 & 5 \end{bmatrix}$$
9. $A = \begin{bmatrix} -3 & 4 \\ -1 & 1 \end{bmatrix}$
35. Prove that if A and B are similar tr(A) = tr(B). (Hint: Find a way from Section 3.2.)

10. $A = \begin{bmatrix} 3 & 1 & 0 \\ 0 & 3 & 1 \\ 0 & 0 & 3 \end{bmatrix}$
11. $A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$
12. $A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 2 & 1 \\ 3 & 0 & 1 \end{bmatrix}$
13. $A = \begin{bmatrix} 1 & 2 & 1 \\ -1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$
14. $A = \begin{bmatrix} 2 & 0 & 0 & 2 \\ 0 & 3 & 2 & 1 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$
15. $A = \begin{bmatrix} 2 & 0 & 0 & 4 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & -2 \end{bmatrix}$
36. $A = \begin{bmatrix} 3 & 1 \\ 0 & -1 \end{bmatrix}, B = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$

In Exercises 16-23, use the method of Example 4.29 to compute the indicated power of the matrix.

16.
$$\begin{bmatrix} -4 & 6 \\ -3 & 5 \end{bmatrix}^9$$
17. $\begin{bmatrix} -1 & 6 \\ 1 & 0 \end{bmatrix}^{10}$
18. $\begin{bmatrix} 4 & -3 \\ -1 & 2 \end{bmatrix}^{-6}$
19. $\begin{bmatrix} 0 & 3 \\ 1 & 2 \end{bmatrix}^k$
20. $\begin{bmatrix} 2 & 1 & 2 \\ 2 & 1 & 2 \\ 2 & 1 & 2 \end{bmatrix}^8$
21. $\begin{bmatrix} 1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}^{2002}$
22. $\begin{bmatrix} 2 & 0 & 1 \\ 1 & 1 & 1 \\ 1 & 0 & 2 \end{bmatrix}^{-5}$
23. $\begin{bmatrix} 1 & 1 & 0 \\ 2 & -2 & 2 \\ 0 & 1 & 1 \end{bmatrix}^{k}$

In Exercises 24-29, find all (real) values of k for which A is diagonalizable.

24.
$$A = \begin{bmatrix} 1 & 1 \\ 0 & k \end{bmatrix}$$
 25. $A = \begin{bmatrix} 1 & k \\ 0 & 1 \end{bmatrix}$ 26. $A = \begin{bmatrix} k & 1 \\ 1 & 0 \end{bmatrix}$ 27. $A = \begin{bmatrix} 1 & 0 & k \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$\mathbf{28.} \ A = \begin{bmatrix} 1 & k & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \qquad \mathbf{29.} \ A = \begin{bmatrix} 1 & 1 & k \\ 1 & 1 & k \\ 1 & 1 & k \end{bmatrix}$$

- **30.** Prove Theorem 4.21(c).
- 31. Prove Theorem 4.22(b).
- 32. Prove Theorem 4.22(c).
- **33.** Prove Theorem 4.22(e).
- 34. If A and B are invertible matrices, show that AB and BA are similar.
- 35. Prove that if A and B are similar matrices, then tr(A) = tr(B). (Hint: Find a way to use Exercise 45) from Section 3.2.)
- In general, it is difficult to show that two matrices are similar. However, if two similar matrices are diagonalizable, the task becomes easier. In Exercises 36-39, show that A and B are similar by showing that they are similar to the same diagonal matrix. Then find an invertible matrix P such that

36.
$$A = \begin{bmatrix} 3 & 1 \\ 0 & -1 \end{bmatrix}, B = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$$

37.
$$A = \begin{bmatrix} 5 & -3 \\ 4 & -2 \end{bmatrix}, B = \begin{bmatrix} -1 & 1 \\ -6 & 4 \end{bmatrix}$$

38.
$$A = \begin{bmatrix} 2 & 1 & 0 \\ 0 & -2 & 1 \\ 0 & 0 & 1 \end{bmatrix}, B = \begin{bmatrix} 3 & 2 & -5 \\ 1 & 2 & -1 \\ 2 & 2 & -4 \end{bmatrix}$$

- **40.** Prove that if A is similar to B, then A^T is similar to B^T .
- **41.** Prove that if A is diagonalizable, so is A^{T} .
- 42. Let A be an invertible matrix. Prove that if A is diagonalizable, so is A^{-1} .
- 43. Prove that if A is a diagonalizable matrix with only one eigenvalue λ , then A is of the form $A = \lambda I$. (Such a matrix is called a scalar matrix.)
- 44. Let A and B be $n \times n$ matrices, each with n distinct eigenvalues. Prove that A and B have the same eigenvectors if and only if AB = BA.
- 45. Let A and B be similar matrices. Prove that the algebraic multiplicities of the eigenvalues of A and B are the same.